

PRELIMINARY MANUAL!

It is important to follow this installation guide during the installation to insure correct installation.
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## Motor connections

Motor cable mounting in box:


## Quick setup of inverter parameters

The inverter is prepared with some parameters already for your easy setup.
For normal setup only mains groups "Operation group" and "Basic functions group (Ba)" are used.
For more information regards the display and keys and groups - see page 4-5.

## Quick setup:

| 1 | When mains and motor are connected - turn on <br> power and ensure that the inverter display light is on. | Inverter always power up in group - Operation. |
| :---: | :--- | :--- |
| 2 | Push - MODE - wanted group | If you can't select new group, you must go to OGr <br> code in operation group and set this to "1". |


|  | Inverter motor settings |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Description | Adjustment group | Display | symbol | Range | Factory set. |
| 3 | Rated motor power | Operation | MkW | -ル゙, | 0.1 to 0.75 kW | 0.4 |
| 4 | Rated motor current | Operation | MrC | -if | 0.1-150.0 A | 2.6 |
| 5 | Rated motor frequency (max) | Operation | FrM | $\mathrm{Frir}^{-}$ | $40.0-400.0 \mathrm{~Hz}$ | 100 |
| 6 | Rated motor voltage | Operation | IoV | 1 Ou | 0, 170-264 V | 230 |
| 7 | Number of motor poles | Basic function | BA. 11 |  | 2-12 poles | 4 |
| 8 | Rated motor slip frequency | Basic function | BA. 12 |  | $0.0-10.0 \mathrm{~Hz}$ * | 4.0 |

* $\mathrm{fs}=\mathrm{fr}-($ rated motor $\mathrm{rpm} \times \mathrm{p} / 120)=50-(1380 \times 4 / 120)=4.0 \mathrm{~Hz}$
$\mathrm{fr}=$ rated motor frequency, $\mathrm{fs}=$ frequency slip (calculated), $\mathrm{p}=$ pole counts in motor.

|  | Inverter settings OPEN direction |  |  |  |  |
| :---: | :--- | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |
|  | Description | Adjustment group | Display symbol | Range | Factory set. |
| 9 | Freq. High OPEN | Operation | 0.00 | 0.0 to Max(FrM) Hz | 60 |
| 10 | Freq. Low OPEN | Basic function | BA.50 | 0.0 to Max(FrM) Hz | 25 |
| 11 | Acc. Time OPEN | Operation | ACC | $0.0-6000.0$ Sec. | 1.0 |
| 12 | Dec. Time High to Low, Opening | Basic function | BA.71 | $0.0-6000.0$ Sec. | 3.0 |
| 13 | Dec. Time to stop | Operation | dEC | $0.0-6000.0$ Sec. | 0.3 |
| 14 | Low speed setp. before open limit | See door control settings below parameter 91 |  | $20 \%$ |  |


|  | Inverter settings CLOSE direction |  |  |  |  |
| :---: | :--- | :---: | :---: | :---: | :---: |
|  | Description | Adjustment group | Display symbol | Range | Factory set. |
| 15 | Freq. High CLOSE | Basic function | BA.51 | 0.0 to Max(FrM) Hz | 50 |
| 16 | Freq. Low CLOSE | Basic function | BA.52 | 0.0 to Max(FrM) Hz | 25 |
| 17 | Acc. Time CLOSE | Basic function | BA.72 | $0.0-6000.0 \mathrm{Sec}$. | 1.0 |
| 18 | Dec. Time High to Low, closing | Basic function | BA.75 | $0.0-6000.0 \mathrm{Sec}$. | 3.0 |
| 19 | Dec. Time to stop | Same as in OPEN direction |  |  | 0.3 |
| 20 | Low speed setp. before close limit | See door control settings parameter 92 |  |  |  |

Opening low speed set point parameter 91

20\% before open limit

## Closing low speed set point parameter 92

|  | Additional settings－for reference only |  |  |  |  |
| :--- | :--- | :---: | :---: | :---: | :---: |
|  | Description | Adjustment group | Display symbol | Range | Factory set． |
|  | Carrier freq． | Control function | Cn．04 | 1 to 15 kHz | 6 |
|  | Forward boost | Operation | FtB | $0.0-20 \%$ | 10.0 |



| No． | Name | Function |
| ---: | :--- | :--- |
| 1 | 7－Segment Display | Displays current operational status and parameter <br> information． |
| 2 | SET Indicator | LED flashes during parameter configuration． |
| 3 | RUN Indicator | LED turns on（steady）during an operation，and flashes <br> during acceleration or deceleration． |
| 4 | FWD Indicator | LED turns on（steady）during forward operation． |
| 5 | REV Indicator | LED turns on（steady）during reverse operation． |

The table below lists the way that the keypad displays characters（letters and numbers）．

| Display | Number／ character | Display | Number／ character | Display | $\begin{aligned} & \text { Number/ } \\ & \text { character } \end{aligned}$ | Display | Number／ character |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 8 | 0 | $日$ | A | $\underline{1}$ | K | U＇1 | U |
| 1 | 1 | $b$ | B | 1 | L | $\square$ | v |
| $\square$ | 2 | 5 | C | $\bar{\square}$ | M | ＂＇ | w |
| $\Xi$ | 3 | － | D | $\pi$ | N | 4 | x |
| 4 | 4 | $E$ | E | $\square$ | o | 3 | Y |
| 5 | 5 | $F$ | F | F－ | P | 三 | Z |
| 5 | 6 | E | G | 9 | Q | 1 | 0 （bit） |
| 7 | 7 | H | H | r | R | 1 | 1 （bit） |
| 日 | 8 | ； | I | 5 | S | － | － |
| 9 | 9 | － | J | t | T | － | － |


| Group | Display | Description |
| :--- | :--- | :--- |
| Operation |  | Configures basic parameters for inverter operation. |
| Drive <br> (Drive) | Configures parameters for basic operations. These include jog <br> operation, torque boost, and other parameters. |  |
| Basic <br> (Basic) | Configures basic parameters, including motor-related <br> parameters and multi-step frequencies. |  |
| Advanced <br> (Advanced) | Configure acceleration or deceleration patterns and to setup <br> frequency limits. |  |
| Control <br> (Control) | Configures functions such as carrier frequency or speed <br> search. |  |
| Input Terminal <br> (Input) | Configures input terminal-related features, including digital <br> multi-functional inputs and analog inputs. |  |
| Output Terminal <br> (Output) | Configures output terminal-related features such as relays and <br> analog outputs. |  |
| Communication <br> (Communication) | Configures communication features for RS-485 or other <br> communication options. <br> ※Available only for models equipped with advanced I/O. |  |
| Application <br> (Application) | Configures PID control-related sequences and operations. |  |
| Protection <br> (Protection) | Configures secondary motor related features. <br> ※The secondary motor (M2) group appears on the keypad only <br> when one of the multi-function input terminals (standard I/O <br> model: In65-67, advanced I/O model: In65-69) has been set to <br> 12 (Secondary motor). |  |
| Secondary Motor <br> (2 Motor) | Configures various features such as parameter setting, |  |

## SAFETY RELAY TURN OFF

Note: The control is lock for electrical driving, if the door is moved manual, when the control is powered.
The display will then show "SER" in display.
This safety is made for a second motor turn off, in case of inverter failure.
Clearing this lock can be done in 2 ways:

1. Move the door away from door limits and make a new power-up.
2. Turn DIL switch no. 1 ON and OFF again.
